

Microcontroller Based Motor Controller Project Report

Kevin Lynch, Nicholas Marchuk, Matthew Elwin

PIC16F1847 Microcontroller-Based Programmable Logic Controller Murat Uzam, 2020-10-23 The PIC16F1847-Based PLC project supports up to 4 analog inputs and 1 analog output, 1 High Speed Counter, 2 PWM (pulse width modulation) outputs, 1 Drum Sequencer Instruction with up to 16 steps, the implementation of Sequential Function Charts (SFCs) with up to 24 steps. This volume presents advanced concepts of the PIC16F1847-Based PLC project and consists of topics like program control, high speed counter and PWM macros. It further explains memory related drum sequencer instruction, sequential functional charts, and analog input and output modules. Aimed at researchers and graduate students in electrical engineering, power electronics, robotics and automation, sensors, this book: Presents program control macros to enable or disable a block of PLC program or to move execution of a program from one place to another. Proposes a High-Speed Counter and four PWM Macros for high speed counting and PWM operations. Develops memory related macros to enable the user to do memory read/write operations. Provides a Drum Sequencer instruction with up to 16 steps and 16 outputs on each step. Discusses the implementation of Sequential Function Chart (SFC) elements with up to 24 steps.

Microcontroller Based DC Motors Lakshminarayana Gadupudi, Heena Chandwani, 2012 Motion control is required in large number of industrial and domestic applications. Such systems employed for motion control are called drives. Direct current (dc) drives are extensively used in industry all over the world. This project takes the area speed control of dc motor using low cost and easily available 8-bit microcontroller. The speed of dc motor is linearly increasing speed and most popular. The dynamic response of dc drive is better than other drives, it has only varying the armature voltage of the motor and there is no harmonics and frequency loss. The speed and current feed-back paths are available from digital signal and analog signal respectively. The proportional integral controller logic is used to calculate the error signal and generate the control signal. The combination of proportional integral controller is used for dynamic response of the closed-loop control system. The AT89S52 microcontroller is used to implementation of proportional integral logic in the C language of KEIL IDE compiler. In-System Programmer is used for loading the program from personal system to 89S52 microcontroller.

Speed Control & Vector Control Design Implementation for Electric Vehicle Project Rami Mourtada, Jaideep Tandon, 1995

8051 Microcontroller David Calcutt, Frederick Cowan, Hassan Parchizadeh, 2003-12-22 The 8051 architecture developed

by Intel has proved to be the most popular and enduring type of microcontroller, available from many manufacturers and widely used for industrial applications and embedded systems as well as being a versatile and economical option for design prototyping, educational use and other project work. In this book the authors introduce the fundamentals and capabilities of the 8051, then put them to use through practical exercises and project work. The result is a highly practical learning experience that will help a wide range of engineers and students to get through the steepest part of the learning curve and become proficient and productive designing with the 8051. The text is also supported by practical examples, summaries and knowledge-check questions. The latest developments in the 8051 family are also covered in this book, with chapters covering flash memory devices and 16-bit microcontrollers. Dave Calcutt, Fred Cowan and Hassan Parchizadeh are all experienced authors and lecturers at the University of Portsmouth, UK. Increase design productivity quickly with 8051 family microcontrollers Unlock the potential of the latest 8051 technology: flash memory devices and 16-bit chips Self-paced learning for electronic designers, technicians and students

Embedded Microcontroller Interfacing Gourab Sen Gupta, 2010-07-15 Mixed-Signal Embedded Microcontrollers are commonly used in integrating analog components needed to control non-digital electronic systems. They are used in automatically controlled devices and products, such as automobile engine control systems, wireless remote controllers, office machines, home appliances, power tools, and toys. Microcontrollers make it economical to digitally control even more devices and processes by reducing the size and cost, compared to a design that uses a separate microprocessor, memory, and input/output devices. In many undergraduate and post-graduate courses, teaching of mixed-signal microcontrollers and their use for project work has become compulsory. Students face a lot of difficulties when they have to interface a microcontroller with the electronics they deal with. This book addresses some issues of interfacing the microcontrollers and describes some project implementations with the Silicon Lab C8051F020 mixed-signal microcontroller. The intended readers are college and university students specializing in electronics, computer systems engineering, electrical and electronics engineering; researchers involved with electronics based system, practitioners, technicians and in general anybody interested in microcontrollers based projects.

Motion Control Report Architecture Technology Architecture Technology Corpor, 2016-01-22 Please note this is a short discount publication. In today's manufacturing environment, Motion Control plays a major role in virtually every project. The Motion Control Report provides a comprehensive overview of the technology of Motion Control: * Design Considerations* Technologies* Methods to Control Motion* Examples of Motion Control in Systems* A Detailed Vendors List

PIC16F1847 Microcontroller-Based Programmable Logic Controller Murat Uzam, 2020-10-23 Programmable logic controllers (PLCs) have been used extensively and are offered in terms of functions, program memories, and the number of inputs/outputs (I/Os), ranging from a few to thousands. With a focus on how to design and implement a PLC, this volume

explains hardware and associated basic concepts of PLC. Authors have used PIC16F1847 microcontroller with: 8192 words of Flash program memory, 1024 bytes of SRAM data memory, 256 bytes of EEPROM data memory, the maximum operating speed of 32 MHz, 16-level deep hardware stack, an enhanced instruction set consisting of 49 single-word instructions. Flowcharts are provided to help the understanding of macros (instructions). Aimed at researchers and graduate students in electrical engineering, power electronics, robotics and automation, sensors, this book: Explains how to design and use a PIC16F1847 microcontroller-based PLC. Provides easy to use software structures written by using the PIC Assembly programming language. Describes a PLC from a designer's perspective. Explains the basic hardware and basic software structures of the PIC16F1847 based PLC. Focuses on concepts like Contact and Relay Based Macros, Flip-Flop Macros, Timer Macros, Counter Macros and Comparison Macros.

Classical and Modern Controls with Microcontrollers Ying Bai, Zvi S. Roth, 2018-12-13 This book focuses on the design, implementation and applications of embedded systems and advanced industrial controls with microcontrollers. It combines classical and modern control theories as well as practical control programming codes to help readers learn control techniques easily and effectively. The book covers both linear and nonlinear control techniques to help readers understand modern control strategies. The author provides a detailed description of the practical considerations and applications in linear and nonlinear control systems. They concentrate on the ARM® Cortex®-M4 MCU system built by Texas Instruments™ called TM4C123GXL, in which two ARM® Cortex®-M4 MCUs, TM4C123GH6PM, are utilized. In order to help the reader develop and build application control software for a specified microcontroller unit. Readers can quickly develop and build their applications by using sample project codes provided in the book to access specified peripherals. The book enables readers to transfer from one interfacing protocol to another, even if they only have basic and fundamental understanding and basic knowledge of one interfacing function. Classical and Modern Controls with Microcontrollers is a powerful source of information for control and systems engineers looking to expand their programming knowledge of C, and of applications of embedded systems with microcontrollers. The book is a textbook for college students majored in CE, EE and ISE to learn and study classical and modern control technologies. The book can also be adopted as a reference book for professional programmers working in modern control fields or related to intelligent controls and embedded computing and applications. Advances in Industrial Control reports and encourages the transfer of technology in control engineering. The rapid development of control technology has an impact on all areas of the control discipline. The series offers an opportunity for researchers to present an extended exposition of new work in all aspects of industrial control.

PIC16F1847 Microcontroller-Based Programmable Logic Controller Murat Uzam, 2020-10-23 The volume focusses on intermediate concepts of the PIC16F1847-Based PLC project, and covers arithmetical operation ability of PLCs, logical function performers and operations like AND, NAND, OR, NOR. Further, it explains shift and rotate macros moving bits in a

register to right or left, and selection macros enabling one value to be selected from several given values according to certain criteria. Demultiplexer circuit is illustrated, which is used to send a signal to one of many devices. Finally, it explains decoder, priority encoder and conversion macros. All the concepts are supported using flowcharts. Aimed at researchers and graduate students in electrical engineering, power electronics, robotics and automation, sensors, this book: Presents arithmetical and logical macros to carry out arithmetical and logical operations to be used for 8-bit or 16-bit variables and/or constant values. Provides shift and rotate macros to do arithmetical or logical shift and rotate operations to be used for 8-bit or 16-bit variables. Proposes selection macros to enable the user to do 8-bit or 16-bit move, load, selection, maximum, minimum, limiting, multiplexing and byte multiplexing operations. Develops demultiplexer macros, decoder macros and priority encoder macros to be used as combinational circuits. Presents conversion macros to provide functions to convert given data from one format to another one.

Microcontroller-based System Controller for a Hybrid Electric Vehicle John Hsu,2002

Embedded Digital Control with Microcontrollers Cem Unsalan,Duygun E. Barkana,H. Deniz Gurhan,2021-03-29
EMBEDDED DIGITAL CONTROL WITH MICROCONTROLLERS Explore a concise and practical introduction to implementation methods and the theory of digital control systems on microcontrollers Embedded Digital Control with Microcontrollers delivers expert instruction in digital control system implementation techniques on the widely used ARM Cortex-M microcontroller. The accomplished authors present the included information in three phases. First, they describe how to implement prototype digital control systems via the Python programming language in order to help the reader better understand theoretical digital control concepts. Second, the book offers readers direction on using the C programming language to implement digital control systems on actual microcontrollers. This will allow readers to solve real-life problems involving digital control, robotics, and mechatronics. Finally, readers will learn how to merge the theoretical and practical issues discussed in the book by implementing digital control systems in real-life applications. Throughout the book, the application of digital control systems using the Python programming language ensures the reader can apply the theory contained within. Readers will also benefit from the inclusion of: A thorough introduction to the hardware used in the book, including STM32 Nucleo Development Boards and motor drive expansion boards An exploration of the software used in the book, including Python, MicroPython, and Mbed Practical discussions of digital control basics, including discrete-time signals, discrete-time systems, linear and time-invariant systems, and constant coefficient difference equations An examination of how to represent a continuous-time system in digital form, including analog-to-digital conversion and digital-to-analog conversion Perfect for undergraduate students in electrical engineering, Embedded Digital Control with Microcontrollers will also earn a place in the libraries of professional engineers and hobbyists working on digital control and robotics systems seeking a one-stop reference for digital control systems on microcontrollers.

Introduction to Microcontroller Programming for Power Electronics Control Applications Mattia Rossi, Nicola Toscani, Marco Mauri, Francesco Castelli Dezza, 2021-09-29 develops key concepts from scratch, including a brief review of control theory and modeling strategies for power electronic-based systems focuses on the LaunchPad™ F28069M board from Texas Instruments™ to provide the reader some basic programming strategies proposes several control problems in terms of power management of RL and RLC loads (e.g. DC-DC converters) and closed-loop control of DC motors examines control schemes as well as the working principles of power converter topologies needed to drive the systems under investigation includes exercises while presenting a processor-in-the loop (PIL) technique to emulate the dynamics of complex systems

PIC Microcontroller Projects in C Dogan Ibrahim, 2014-04-16 Extensively revised and updated to encompass the latest developments in the PIC 18FXXX series, this book demonstrates how to develop a range of microcontroller applications through a project-based approach. After giving an introduction to programming in C using the popular mikroC Pro for PIC and MPLAB XC8 languages, this book describes the project development cycle in full. The book walks you through fully tried and tested hands-on projects, including many new, advanced topics such as Ethernet programming, digital signal processing, and RFID technology. This book is ideal for engineers, technicians, hobbyists and students who have knowledge of the basic principles of PIC microcontrollers and want to develop more advanced applications using the PIC18F series. This book Includes over fifty projects which are divided into three categories: Basic, Intermediate, and Advanced. New projects in this edition: Logic probe Custom LCD font design Hi/Lo game Generating various waveforms in real-time Ultrasonic height measurement Frequency counter Reaction timer GPS projects Closed-loop ON/OFF temperature control Bluetooth projects (master and slave) RFID projects Clock using Real-time-clock (RTC) chip RTC alarm project Graphics LCD (GLCD) projects Barometer+thermometer+altimeter project Plotting temperature on GLCD Ethernet web browser based control Ethernet UDP based control Digital signal processing (Low Pass Filter design) Automotive LIN bus project Automotive CAN bus project Multitasking projects (using both cooperative and Round-robin scheduling) Unipolar stepper motor projects Bipolar stepper motor projects Closed-loop ON/OFF DC motor control A clear introduction to the PIC 18FXXX microcontroller's architecture Covers developing wireless and sensor network applications, SD card projects, and multi-tasking; all demonstrated with the block and circuit diagram, program description in PDL, program listing, and program description Includes more than 50 basic, intermediate, and advanced projects

Running Small Motors with PIC Microcontrollers Harprit Singh Sandhu, 2009-08-24 Program PIC microcontrollers to drive small motors Get your motors running in no time using this easy-to-follow guide. Detailed circuit diagrams and hands-on tutorials show you, step by step, how to program PIC microcontrollers to power a wide variety of small motors. You'll learn how to configure all the hardware and software components and test, troubleshoot, and debug your work. Running

Small Motors with PIC Microcontrollers is filled with more than 2,000 lines of PicBasic Pro code you can use right away. Use PIC microcontrollers to control all kinds of small motors, including: Model aircraft R/C servos Small DC motors Servo DC motors with quadrature encoders Bipolar stepper motors Small AC motors, solenoids, and relays

Electrical Machines Charles Seymour Siskind,1959

An Intel 80C196KB Microcontroller Based Implementation of the MVVS Algorithm for the Cornell Electric Vehicle

William Dill,1993

Embedded Computing and Mechatronics with the PIC32 Microcontroller Kevin Lynch,Nicholas Marchuk,Matthew Elwin,2015-12-08 For the first time in a single reference, this book provides the beginner with a coherent and logical introduction to the hardware and software of the PIC32, bringing together key material from the PIC32 Reference Manual, Data Sheets, XC32 C Compiler User's Guide, Assembler and Linker Guide, MIPS32 CPU manuals, and Harmony documentation. This book also trains you to use the Microchip documentation, allowing better life-long learning of the PIC32. The philosophy is to get you started quickly, but to emphasize fundamentals and to eliminate magic steps that prevent a deep understanding of how the software you write connects to the hardware. Applications focus on mechatronics: microcontroller-controlled electromechanical systems incorporating sensors and actuators. To support a learn-by-doing approach, you can follow the examples throughout the book using the sample code and your PIC32 development board. The exercises at the end of each chapter help you put your new skills to practice. Coverage includes: A practical introduction to the C programming language Getting up and running quickly with the PIC32 An exploration of the hardware architecture of the PIC32 and differences among PIC32 families Fundamentals of embedded computing with the PIC32, including the build process, time- and memory-efficient programming, and interrupts A peripheral reference, with extensive sample code covering digital input and output, counter/timers, PWM, analog input, input capture, watchdog timer, and communication by the parallel master port, SPI, I2C, CAN, USB, and UART An introduction to the Microchip Harmony programming framework Essential topics in mechatronics, including interfacing sensors to the PIC32, digital signal processing, theory of operation and control of brushed DC motors, motor sizing and gearing, and other actuators such as stepper motors, RC servos, and brushless DC motors For more information on the book, and to download free sample code, please visit <http://www.nu32.org> Extensive, freely downloadable sample code for the NU32 development board incorporating the PIC32MX795F512H microcontroller Free online instructional videos to support many of the chapters

Scientific and Technical Aerospace Reports ,1995

Microprocessor-Based Control Systems N.K. Sinha,2012-12-06 Recent advances in LSI technology and the consequent availability of inexpensive but powerful microprocessors have already affected the process control industry in a significant manner. Microprocessors are being increasingly utilized for improving the performance of control systems and making them

more sophisticated as well as reliable. Many concepts of adaptive and learning control theory which were considered impractical only 20 years ago are now being implemented. With these developments there has been a steady growth in hardware and software tools to support the microprocessor in its complex tasks. With the current trend of using several microprocessors for performing the complex tasks in a modern control system, a great deal of emphasis is being given to the topic of the transfer and sharing of information between them. Thus the subject of local area networking in the industrial environment has become assumed great importance. The object of this book is to present both hardware and software concepts that are important in the development of microprocessor-based control systems. An attempt has been made to obtain a balance between theory and practice, with emphasis on practical applications. It should be useful for both practicing engineers and students who are interested in learning the practical details of the implementation of microprocessor-based control systems. As some of the related material has been published in the earlier volumes of this series, duplication has been avoided as far as possible.

Rehabilitation R & D Progress Reports ,1997

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